

Solitary wave solutions for some fractional evolution equations via new Kudryashov approach

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In this work, we construct solitary wave solutions for fractional nonlinear evolution equations in wave theory, which are used to explain the physical wave formation structures on the surface and in the water, namely the time fractional fifth-order Sawada-Kotera equation and the $(4 + 1)$ dimensional space-time fractional Fokas equation by Kudryashov method with a new function. The aim of this study is to obtain new solitary solutions by reducing the number of calculations. As a result, new types of solitary wave solutions are obtained via Mathematica 11.3 package program. Here the fractional derivative is described in beta sense.

Keywords: New Kudryashov approach; solitary wave solutions; beta-derivative; the time-fractional fifth-order Sawada–Kotera equation and the $(4 + 1)$ -dimensional space-time fractional Fokas

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1. Introduction

Fractional order partial differential equations have been among the hot topics discussed recently in books [1, 2] and many research papers [3–34]. Solitary wave solutions are considered a significant challenge in many disciplines, ranging from biology, quantum chemistry, electrodynamics, viscoelasticity, image processing, systems identification and optical fibers to fluid mechanics. Well known traditional approaches based on auxiliary equations are known to have efficiencies for obtaining solitary wave solutions. Fractional order equations are currently used in several modern technologies of the twenty first century such as optical imaging, the study of waves on dam water, solid state physics and swinging in quantum mechanics. Since such equations contain a wide range of applications, it is important for researchers to construct and apply robust algorithms for the solutions of fractional equations. In many fields of science and engineering, especially in physical problems, several techniques have been proposed to obtain exact or approximate solutions, such as the tanh – sech method [3, 4], q-homotopy analysis method (q-HAM) [5–7], residual power series method [6], the sub-equation method [6, 8, 9], improved Bernoulli sub-equation function method [10], the reduced differential transform method [11], the generalized $\exp-\phi(\xi)$ - expansion and improved F-expansion method [12], the extended fractional $D_\xi^\alpha G/G$ -expansion method [13], Jacobi elliptic functions [14], the modified exponential function method [15], Sine-Gordon expansion method [16, 17], the exponential rational function method [18], the general Riccati equation method [19], generalized Kudryashov method [20, 21], the direct truncation method [22], the modified Kudryashov method [4, 23–29] and so on. Recently, Kudryashov [30, 31] proposed a new method based on arbitrary refractive index and pole order principle. The novelty of this approach is the introduction of producing a convenient logistic function to obtain solitary wave solutions of nonlinear partial differ-

ential equations. The main starting point of the method is based on the efficiency of the function $Q(\eta) = (a \exp(\eta) + b \exp(-\eta))^{-1}$ where a and b are parameters. Besides the methods applied when solving fractional equations, the diversity of fractional derivatives used is also an important part of research. While some researchers preferred the Riemann-Liouville type derivative in their studies [3, 5, 12, 14, 19, 21], some researchers preferred the Caputo type derivative [5, 32, 33]. Recently, Atangana *et al.* [33, 34] introduced a new derivative definition: the beta-fractional derivative.

In many previous studies the time-fractional fifth-order Sawada-Kotera equation and the time fractional $(4 + 1)$ -dimensional Fokas equation have been handled with the sense of Jumarie's Riemann-Liouville derivative [3, 5, 6, 8, 12, 19]. Then, solitary solutions have been obtained by creating auxiliary equations in accordance with the method's own algorithm for the equations, which are reduced by using the traveling wave transformations in the traditional methods applied. These equations, which have important roles in wave theory, are used to explain the physical wave formation structures that occur on the surface and in the water. In particular, whereas Sawada-Kotera equation delineates a merely inelastic scattering transaction, Fokas equation is driven to qualify the surface waves and internal waves in channels or narrows of varying width and depth. The main motivation of this work is to obtain new solitary wave solutions with less computation. Hence, in this study, we apply the newest version of Kudryashov's algorithm with arbitrary refractive index [30, 31] for efficient computation of these equations using the beta derivative.

2. Motivation

2.1. Beta Derivative Definition

Let u be a function, $u : [a, \infty] \rightarrow \mathbb{R}$. In [34] Atangana *et al.* proposed the beta derivative as following:

$${}_0^A D_x^\alpha [u(x)] = \lim_{\zeta \rightarrow 0} \frac{u \left[x + \zeta \left(x + \frac{1}{\Gamma(\alpha)} \right)^{1-\alpha} \right] - u[x]}{\zeta}, \quad (1)$$

for all $x \geq a$, $0 < \alpha \leq 1$. If the limit of Eq. (1) exists, f is said to be beta-differentiable. Beta derivative definition does not depend on the interval. If the function is differentiable at a zero point Eq. (1) is not equal to zero.

Assuming that, u and $v \neq 0$ are two functions beta-differentiable with $0 < \alpha \leq 1$ then, the beta derivative possesses the next properties:

$$1) {}_0^A D_x^\alpha [au(x) + bv(x)] = a {}_0^A D_x^\alpha [u(x)] + b {}_0^A D_x^\alpha [v(x)], \quad (2)$$

for all a and b real numbers.

$$2) \quad {}_0^A D_x^\alpha [d] = 0, \quad (3)$$

with d a given constant..

$$3) {}_0^A D_x^\alpha [u(x)v(x)] = v(x) {}_0^A D_x^\alpha [u(x)] + u(x) {}_0^A D_x^\alpha [v(x)], \quad (4)$$

$$4) {}_0^A D_x^\alpha \left[\frac{u(x)}{v(x)} \right] = \frac{v(x) {}_0^A D_x^\alpha [u(x)] - u(x) {}_0^A D_x^\alpha [v(x)]}{v^2(x)}. \quad (5)$$

Considering from Eq. (1) the factor $\zeta = (x + [1/\Gamma(\alpha)])^{1-\alpha} h$, we see that $h \rightarrow 0$, when $\zeta \rightarrow 0$, therefore we obtain

$${}_0^A D_x^\alpha [u(x)] = \left(x + \frac{1}{\Gamma(\alpha)} \right)^{1-\alpha} \frac{du(x)}{dx}. \quad (6)$$

Introducing

$$\eta = \frac{\kappa}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha, \quad (7)$$

where κ is constant, we reach the equation

$${}_0^A D_x^\alpha [u(\eta)] = \kappa \frac{du(\eta)}{d\eta}. \quad (8)$$

3. Methodology

3.1. Methodolgy to figure out the solitary wave solitons

The main steps of the proposed method are represented as follows:

Step 1: Initially, we consider the general form of nonlinear fractional partial differential equations given by

$$\varphi \left(v, v_x, v_y, \dots, v_t, v_{xx}, v_{xy}, \dots, D_y^\alpha v, D_z^\alpha v, \dots, D_t^\alpha v, \dots \right) \quad (9)$$

$$D_y^{2\alpha} v, D_z^{2\alpha} v, \dots, D_t^{2\alpha} v, \dots = 0, \quad 0 < \alpha \leq 1,$$

where $v = (x, y, z, w, t)$ is an unknown function and φ is a polynomial in v and its various partial derivatives in that the highest-order derivatives and nonlinear terms are involved. Additionally $D_t^\alpha v, D_y^\alpha v, D_z^\alpha v, D_w^\alpha v, \dots$ are beta derivatives of v .

Step 2: Secondly, we presume that the following traveling wave transformation

$$v(x, y, z, w, t) = v(\eta), \quad (10)$$

$$\eta = kx - \left(\frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\gamma}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha \right), \quad (11)$$

reduces the fractional order of the differential Eq. (9) into an ordinary differential equation. Here, k, β, γ, σ and c are arbitrary constants. Then, by using the chain rule we have,

$$\mu(v, v', v'', \dots) = 0. \quad (12)$$

Step 3: By the proposed method, we consider that Eq. (12) has a solution of the form:

$$v(\eta) = \sum_{m=0}^N a_m Q^m(\eta), \quad (13)$$

where

$$Q(\eta) = \frac{1}{a \exp(\eta) + b \exp(-\eta)}, \quad (14)$$

$Q(\eta)$ adopts the given ordinary differential equation:

$$Q_\eta^2 = Q^2(1 - \chi Q^2), \quad (15)$$

where $\chi = 4ab$. The main feature of $Q(\eta)$ is that higher order odd derivatives includes both Q (and its powers) and, Q_η , while the even derivatives have only Q and its powers. Therefore, the expressions of the higher order derivatives from second to fifth order are

$$Q_{\eta\eta} = Q - 2\chi Q^3, \quad (16)$$

$$Q_{\eta\eta\eta} = Q_\eta - 6\chi Q^2 Q_\eta, \quad (17)$$

$$Q_{\eta\eta\eta\eta} = Q - 20\chi Q^3 + 24\chi^2 Q^5, \quad (18)$$

$$Q_{\eta\eta\eta\eta\eta} = Q_\eta - 60\chi Q^2 Q_\eta + 120\chi^2 Q^4 Q_\eta, \quad (19)$$

$$Q_{\eta\eta\eta\eta\eta\eta} = Q - 182\chi Q^3 + 840\chi^2 Q^5 - 720\chi^4 Q^7. \quad (20)$$

Then, taking into account the polynomial $v(\eta) = \sum_{m=0}^N a_m Q^m(\eta)$ and assuming. That the pole order of the equation is N by means of homogenous balance principle, we can find the relations of derivatives $v_\eta, v_{\eta\eta}, v_{\eta\eta\eta}, v_{\eta\eta\eta\eta}$ and $v_{\eta\eta\eta\eta\eta}$ as follows:

$$v_\eta = \sum_{m=1}^N a_m m Q^{m-1} Q_\eta, \quad (21)$$

$$v_{\eta\eta} = \sum_{m=1}^N a_m [m^2 Q^m - m^2 \chi Q^{m+2} - m \chi Q^{m+2}], \quad (22)$$

$$v_{\eta\eta\eta} = \sum_{m=1}^N a_m [m^3 Q^{m-1} - \chi m^2 (m+2) Q^{m+1} - \chi m (m+2) Q^{m+1}] Q_{\eta}, \tag{23}$$

$$v_{\eta\eta\eta\eta} = \sum_{m=1}^N m a_m [m^3 + (m^3 \chi^2 + 6m^2 \chi^2 + 11m \chi^2 + 6\chi^2) Q^4 - (2m^3 \chi + 6m^2 \chi + 8m \chi + 4\chi) Q^2] Q^m, \tag{24}$$

$$v_{\eta\eta\eta\eta\eta} = \sum_{m=1}^N m a_m Q^{m-1} [m^4 + (m+4)(m^3 \chi^2 + 6m^2 \chi^2 + 11m \chi^2 + 6\chi^2) Q^4 - (j+2)(2m^3 \chi 6m^2 \chi + 8m \chi + 4\chi) Q^2] Q_{\eta}. \tag{25}$$

Step 4: Inserting Eq. (13) and (21)-(25) into Eq. 12 we have the reduced form of the equation into polynomial which consists of Q and Q_{η} . Next, matching each coefficient for different powers of $Q^n Q_{\eta}^h$ ($h = 0, 1$) we obtain a set of algebraic equations. Finally, by solving this system, we obtain the solitary wave solutions of Eq. (12).

4. Applications

4.1. The time-fractional fifth-order Sawada-Kotera Equation

The time-fractional fifth-order Sawada-Kotera equation is a significant unidirectional nonlinear evolution equation appurtenant a fully integrable hierarchy of higher fractional order KdV equations. In other words, it is a special case of the KdV equations as follows:

$$D_t^{\alpha} v + v_{xxxxx} + 45v_x v^2 + 15(v_x v_{xx} + v v_{xxx}) = 0, \tag{26}$$

where $0 < \alpha \leq 1$. To apply the aforesaid method, first, we use the fractional beta transformation:

$$v(x, t) = v(\eta), \quad \eta = kx - \frac{\delta}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^{\alpha}. \tag{27}$$

After this wave transformation, Eq. (26) is reduced into the following ODE:

$$-\delta v' + k^5 v^{(v)} + 45v' v^2 + 15(v' v'' + v v''') = 0. \tag{28}$$

By using the homogenous balance principle in Eq. (28), balancing the highest order derivative and nonlinear term, we obtain the pole order $N = 2$. Then, the second degree auxilary polynomial can be written as follows:

$$v(\eta) = a_0 + a_1 Q(\eta) + a_2 Q^2(\eta), \tag{29}$$

where

$$Q(\eta) = \frac{1}{a \exp(\eta) + b \exp(-\eta)}$$

adopts the differential equation:

$$Q_{\eta}^2 = Q^2(1 - \chi Q^2),$$

with $\chi = 4ab$.

Calculating the derivatives of Eq. (29) from first to fifth order the following equations are obtained:

$$\begin{aligned} v'(\eta) &= Q_{\eta} [a_1 + 2a_2 Q(\eta)], \\ v''(\eta) &= a_1 (Q_{\eta}(\eta) - 2Q^3(\eta)) + a_2 (4Q^2(\eta) - 8\chi Q^4(\eta)), \\ v'''(\eta) &= Q_{\eta} [a_1 (1 - 6\chi Q^2(\eta)) + a_2 (8Q(\eta) - 24\chi Q^3(\eta))], \\ v^{(v)}(\eta) &= Q_{\eta} [a_1 (1 + 120\chi^2 Q^4(\eta) - 60\chi Q^2(\eta)) + 2a_2 (16 + 300\chi^2 Q^4(\eta) - 240\chi Q^2(\eta)) Q(\eta)]. \end{aligned} \tag{30}$$

Substituting Eq. (29) and Eqs. (30) into Eq. (28), we obtain an equation which contains the powers of Q . Then, by linking all the same powers of Q and equating all the coefficients to zero, we get the following algebraic system:

$$\begin{aligned} k^5 a_1 - \delta a_1 + 15a_0 a_1 + 45a_0^2 a_1 &= 0, \\ 30a_1^2 + 90a_0 a_1^2 + 32k^5 a_2 - 2\delta a_2 + 120a_0 a_2 + 90a_0^2 a_2 &= 0, \\ -60k^5 \chi a_1 - 90\chi a_0 a_1 + 45a_1^3 + 225a_1 a_2 + 270a_0 a_1 a_2 &= 0, \\ a_1^2 - 90\chi a_1^2 - 480k^5 \chi a_2 - 360\chi a_0 a_2 + 180a_1^2 a_2 + 240a_2^2 + 180a_0 a_2^2 &= 0, \\ 120k^5 \chi^2 a_1 - 60a_1 a_2 - 570\chi a_1 a_2 + 225a_1 a_2^2 &= 0, \\ 600k^5 \chi^2 a_2 - 600\chi a_2^2 + 90a_2^3 &= 0. \end{aligned}$$

Finally, solving this system we get seven cases of solitary wave solutions of the Eq. (26) as: **Case I:**

$$\begin{aligned} a_0 &= -\frac{14}{15}, \quad a_1 = 0, \quad a_2 = \frac{14\chi}{3}, \quad k = \sqrt[5]{\frac{7}{5}}, \quad \delta = \frac{28}{5}, \\ v(\eta) &= -\frac{14}{15} + \frac{14}{3}\chi \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= -\frac{14}{15} + \frac{14}{3}\chi \left(\frac{4a}{4a^2 e^{\sqrt[5]{\frac{7}{5}}x - \frac{28}{5\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{-\sqrt[5]{\frac{7}{5}}x + \frac{28}{5\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (31)$$

Case II:

$$\begin{aligned} a_0 &= -\frac{14}{15}, \quad a_1 = 0, \quad a_2 = \frac{14\chi}{3}, \quad k = -\sqrt[5]{\frac{7}{5}}, \quad \delta = \frac{28}{5}, \\ v(\eta) &= -\frac{14}{15} + \frac{14}{3}\chi \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= -\frac{14}{15} + \frac{14}{3}\chi \left(\frac{4a}{4a^2 e^{-\sqrt[5]{\frac{7}{5}}x - \frac{28}{5\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{\sqrt[5]{\frac{7}{5}}x + \frac{28}{5\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (32)$$

Case III:

$$\begin{aligned} a_0 &= -\frac{4}{3}, \quad a_1 = 0, \quad a_2 = -\frac{2}{3}(-5\chi + \sqrt{10}\chi), \quad k = 1, \quad \delta = 16, \\ v(\eta) &= -\frac{4}{3} + \frac{10 - 2\sqrt{10}}{3}\chi \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= -\frac{4}{3} + \frac{10 - 2\sqrt{10}}{3}\chi \left(\frac{4a}{4a^2 e^{x - \frac{16}{\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{-x + \frac{16}{\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (33)$$

Case IV:

$$\begin{aligned} a_0 &= \frac{4}{3}, \quad a_1 = 0, \quad a_2 = \frac{2}{3}(-5\chi + \sqrt{10}\chi), \quad k = 1, \quad \delta = 16, \\ v(\eta) &= \frac{4}{3} - \frac{10 - 2\sqrt{10}}{3}\chi \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= \frac{4}{3} - \frac{10 - 2\sqrt{10}}{3}\chi \left(\frac{4a}{4a^2 e^{x - \frac{16}{\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{-x + \frac{16}{\alpha}(t + \frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (34)$$

Case V:

$$\begin{aligned} a_0 &= -\frac{40}{21}, \quad a_1 = 0, \quad a_2 = \frac{20\chi}{3}, \quad k = 0, \quad \delta = \frac{2400}{49}, \\ v(\eta) &= -\frac{40}{21} - \frac{20}{3}\chi \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= -\frac{40}{21} - \frac{20}{3}\chi \left(\frac{4a}{4a^2e^{-\frac{2400}{49\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{\frac{2400}{49\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (35)$$

Case VI:

$$\begin{aligned} a_0 &= -\frac{4}{3}, \quad a_1 = 0, \quad a_2 = \frac{2}{3}(5\chi - \sqrt{10}), \quad k = 1, \quad \delta = 16, \\ v(\eta) &= -\frac{4}{3} + \frac{10\chi - 2\sqrt{10}}{3} \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= -\frac{4}{3} + \frac{10\chi - 2\sqrt{10}}{3} \left(\frac{4a}{4a^2e^{x-\frac{16}{\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{-x+\frac{16}{\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (36)$$

Case VII:

$$\begin{aligned} a_0 &= \frac{4}{3}, \quad a_1 = 0, \quad a_2 = \frac{2}{3}(5\chi + \sqrt{10}), \quad k = 1, \quad \delta = 16, \\ v(\eta) &= \frac{4}{3} + \frac{10\chi + 2\sqrt{10}}{3} \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}} \right)^2, \\ v(x, t) &= \frac{4}{3} + \frac{10\chi + 2\sqrt{10}}{3} \left(\frac{4a}{4a^2e^{x-\frac{16}{\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha} + \chi e^{-x+\frac{16}{\alpha}(t+\frac{1}{\Gamma(\alpha)})^\alpha}} \right)^2. \end{aligned} \quad (37)$$

4.2. The (4 + 1)-dimensional space-time fractional Fokas equation

The (4 + 1)-dimensional space-time fractional Fokas equation has the form:

$$4 \frac{\partial^{2\alpha} v}{\partial t^\alpha \partial x^\alpha} - \frac{\partial^{4\alpha} v}{\partial x^{3\alpha} \partial y^\alpha} + \frac{\partial^{4\alpha} v}{\partial x^\alpha \partial y^{3\alpha}} + 12 \frac{\partial^\alpha v}{\partial x^\alpha} \frac{\partial^\alpha v}{\partial y^\alpha} + 12v \frac{\partial^{2\alpha} v}{\partial x^\alpha \partial y^\alpha} - 6 \frac{\partial^{2\alpha} v}{\partial z^\alpha \partial w^\alpha} = 0, \quad t > 0, \quad 0 < \alpha \leq 1. \quad (38)$$

First, we apply the fractional beta transformation:

$$v(x, y, z, w, t) = v(\eta), \quad (39)$$

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\gamma}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha. \quad (40)$$

Then, Eq. (38) is reduced into the following ODE:

$$(4c\delta - 6\gamma\sigma) v'' + (\beta^3\delta - \delta^3\beta) v^{(iv)} + 12\delta\beta (vv')' = 0. \quad (41)$$

We integrate Eq. (41) once, taking the integration constant zero for simplicity. Then, we obtain the following ODE:

$$(4c\delta - 6\gamma\sigma) v' + (\beta^3\delta - \delta^3\beta) v''' + 12\delta\beta (vv') = 0. \quad (42)$$

Again, using the homogenous balance principle and balancing the terms v''' and vv' we calculate the pole order $N = 2$. Then, we can write the auxiliary polynomial as:

$$v(\eta) = a_0 + a_1 Q(\eta) + a_2 Q^2(\eta), \quad (43)$$

where

$$Q(\eta) = \frac{1}{a \exp(\eta) + b \exp(-\eta)}$$

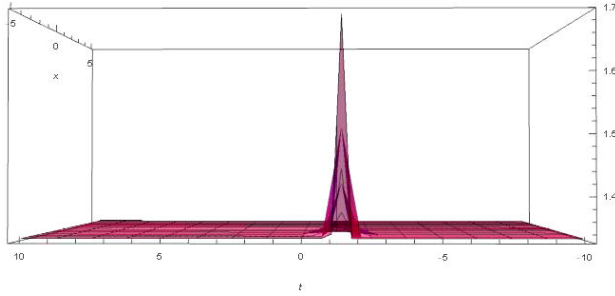


FIGURE 1. Three-dimensional plot of the solution (37) for $\alpha = 1$, $\chi = 4$ and $a = 1$.

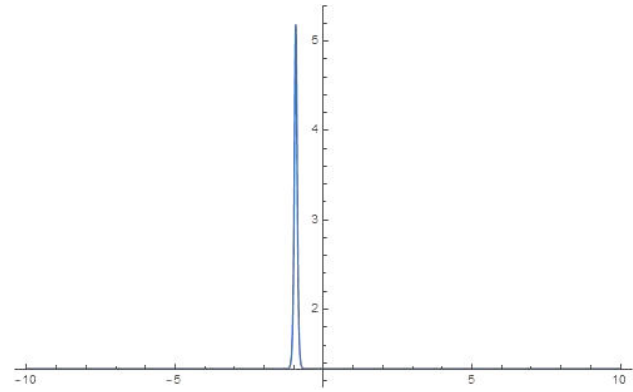


FIGURE 2. Plot of the solution (37) for $\alpha = 1$, $\chi = 4$ and $a = 1$.

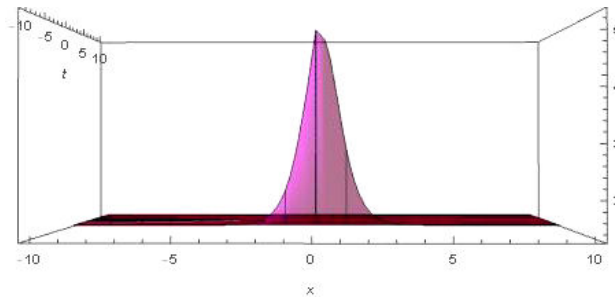


FIGURE 3. Three-dimensional plot of the solution (37) for $\alpha = 1/2$, $\chi = 4$ and $a = 1$.

adopts the equation:

$$Q_\eta^2 = Q^2(1 - \chi Q^2), \tag{44}$$

with $\chi = 4ab$.

The first and third derivatives of Eq. (43) are sufficient for the solutions. Hence, we take them as follows:

$$\begin{aligned} v'(\eta) &= Q_\eta [a_1 + 2a_2 Q(\eta)], \\ v'''(\eta) &= Q_\eta [a_1 (1 - 6\chi Q^2(\eta)) + a_2 (8Q(\eta) - 24\chi Q^3(\eta))]. \end{aligned} \tag{45}$$

Substituting Eq. (43) and Eqs. (45) into Eq. (42), we get an equation including the powers of Q . Then collecting the terms with the same power of Q and equating the coefficients to zero, we obtain the following algebraic system:

$$\begin{aligned} 4c\delta a_1 + \beta^3 \delta a_1 + \beta \delta^3 a_1 - 6\gamma \sigma a_1 + 12\beta \delta a_0 &= 0, \\ 12\beta \delta a_1^2 + 8c\delta a_2 + 8\beta^3 \delta a_2 + 8\beta \delta^3 a_2 + 8\beta \delta^3 a_2 - 12\gamma \sigma a_2 + 24\beta \delta a_0 a_2 &= 0, \\ -6\beta^3 \delta \chi a_1 - 6\beta \delta^3 \chi a_1 + 36\beta \delta a_1 a_2 &= 0, \\ -24\beta^3 \delta \chi a_2 - 24\beta \delta^3 \chi a_2 + 24\beta \delta a_2^2 &= 0. \end{aligned}$$

Solving this system we get ten cases of solitary wave solutions of the Eq. (38) as:

Case I:

$$\begin{aligned} a_0 = a_0, \quad a_1 = 0, \quad a_2 = (\beta^2 + \delta^2) \chi, \quad \sigma = \frac{2\delta (c + \beta^2 + \beta \delta^2 + 3\beta a_0)}{3\gamma}, \\ v(\eta) = a_0 - (\beta^2 + \delta^2) \chi \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)^2, \quad v(x, y, z, w, t) = a_0 - (\beta^2 + \delta^2) \chi A^2, \end{aligned} \tag{46}$$

where

$$A = \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\gamma}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{2\delta(c + \beta^2 + \beta\delta^2 + 3\beta a_0)}{3\gamma\alpha} \left(w + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)}\right)^\alpha.$$

Case II:

$$a_0 = a_0, \quad a_1 = 0, \quad a_2 = \beta^2\chi, \quad \delta = 0, \quad \gamma = 0, \quad v(x, y, z, w, t) = a_0 - \beta^2\chi A^2, \quad (47)$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}}\right)$$

and

$$\eta = \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)}\right)^\alpha. \quad (48)$$

Case III:

$$a_0 = \frac{-c - \beta^3 - \beta\delta^2}{3\beta}, \quad a_1 = 0, \quad a_2 = (\beta^2 + \delta^2)\chi, \quad \gamma = 0,$$

$$v(x, y, z, w, t) = \frac{-c - \beta^3 - \beta\delta^2}{3\beta} + (\beta^2 + \delta^2)\chi A^2, \quad (49)$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}}\right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)}\right)^\alpha.$$

Case IV:

$$a_0 = a_0, \quad a_1 = 0, \quad a_2 = (\beta^2 + \delta^2)\chi, \quad \sigma = 1, \quad \gamma = \frac{2}{3}\delta(c + \beta^3 + \beta\delta^2 + 3\beta a_0),$$

$$v(x, y, z, w, t) = a_0 - (\beta^2 + \delta^2)\chi A^2, \quad (50)$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}}\right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{2\delta(c + \beta^3 + \beta\delta^2 + 3\beta a_0)}{3\alpha} \left(z + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{1}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)}\right)^\alpha.$$

Case V:

$$a_0 = a_0, \quad a_1 = 0, \quad a_2 = (\beta^2 + 1)\chi, \quad \delta = 1, \quad \sigma = \frac{2\delta}{3\gamma}(c + \beta^3 + \beta\delta^2 + 3\beta a_0),$$

$$v(x, y, z, w, t) = a_0 + (\beta^2 + 1)\chi A^2, \quad (51)$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}}\right)$$

and

$$\eta = \frac{1}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{\gamma}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{2\delta(c + \beta^3 + \beta\delta^2 + 3\beta a_0)}{3\gamma\alpha} \left(w + \frac{1}{\Gamma(\alpha)}\right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)}\right)^\alpha.$$

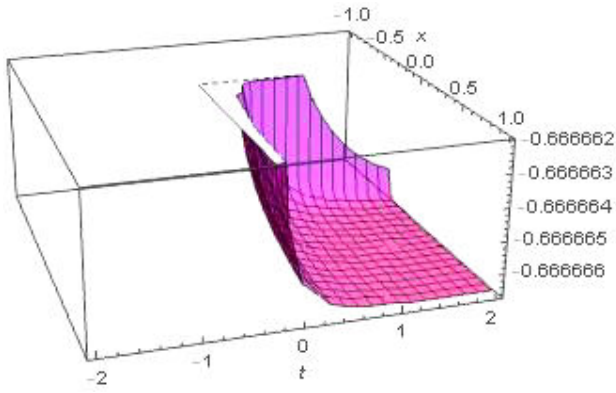


FIGURE 4. 3D Plot of the solution (49) for $\alpha = 0.25$, $\chi = 4$ and $a = 1$.

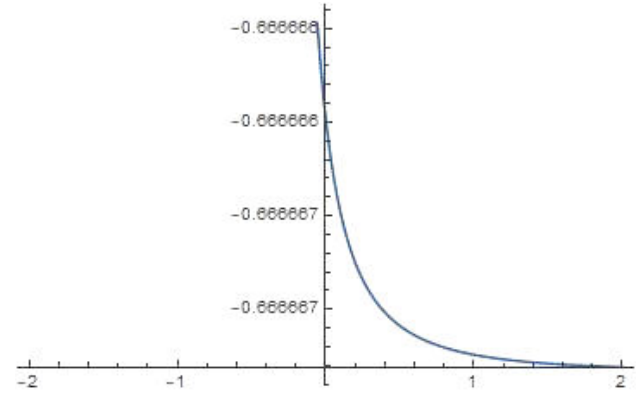


FIGURE 5. Plot of the solution (49) for $\alpha = 0.25$, $\chi = 4$ and $a = 1$.

Case VI:

$$a_0 = -\frac{c + \beta + \beta^2}{3\beta}, \quad a_1 = 0, \quad a_2 = (\beta^2 + 1)\chi, \quad \delta = 1, \quad \gamma = 0,$$

$$v(x, y, z, w, t) = -\frac{c + \beta + \beta^2}{3\beta} + (\beta^2 + 1)\chi A^2, \quad (52)$$

where

$$A = \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{1}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha.$$

Case VII:

$$a_0 = a_0, \quad a_1 = 0, \quad a_2 = (\beta^2 + \delta^2)\chi, \quad \gamma = 1, \quad \sigma = \frac{2}{3}\delta(c + \beta^3 + \beta\delta^2 + 3\beta a_0),$$

$$v(x, y, z, w, t) = a_0 + (\beta^2 + \delta^2)\chi A^2, \quad (53)$$

where

$$A = \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{1}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{2\delta(c + \beta^3 + \beta\delta^2 + 3\beta a_0)}{3\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha.$$

Case VIII:

$$a_0 = a_0, \quad a_1 = 0, \quad a_2 = (1 + \delta^2)\chi, \quad \beta = 1, \quad \sigma = \frac{2\delta}{3\gamma}(1 + c + \delta^2 + 3a_0),$$

$$v(x, y, z, w, t) = a_0 + (1 + \delta^2)\chi A^2, \quad (54)$$

where

$$A = \left(\frac{4a}{4a^2 e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\beta}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\gamma}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{2\delta(1 + c + \delta^2 + 3a_0)}{3\gamma\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha.$$

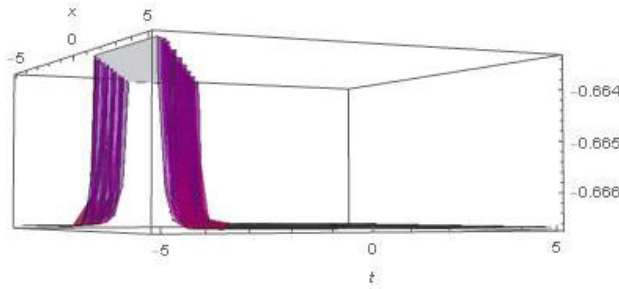


FIGURE 6. 3D Plot of the solution (56) for $\alpha = 1, \chi = 4$ and $a = 1$.

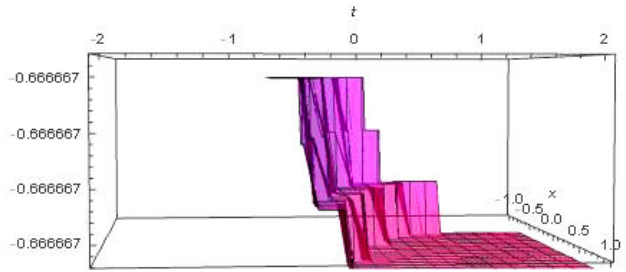


FIGURE 7. 3D Plot of the solution (56) for $\alpha = 1/2, \chi = 4$ and $a = 1$.

Case IX:

$$a_0 = -\frac{c+1+\delta^2}{3}, \quad a_1 = 0, \quad a_2 = (\delta^2+1)\chi, \quad \beta = 1, \quad \gamma = 0,$$

$$v(x, y, z, w, t) = -\frac{c+1+\delta^2}{3} + (\delta^2+1)\chi A^2, \tag{55}$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{\delta}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{1}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{\sigma}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha.$$

Case X:

$$a_0 = -\frac{1+2c}{6}, \quad a_1 = 0, \quad a_2 = 2\chi, \quad \delta = 1, \quad \beta = 1, \quad \gamma = 1, \quad \sigma = 1,$$

$$v(x, y, z, w, t) = -\frac{1+2c}{6} + 2\chi A^2, \tag{56}$$

where

$$A = \left(\frac{4a}{4a^2e^\eta + \chi e^{-\eta}} \right)$$

and

$$\eta = \frac{1}{\alpha} \left(x + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{1}{\alpha} \left(y + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{1}{\alpha} \left(z + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{1}{\alpha} \left(w + \frac{1}{\Gamma(\alpha)} \right)^\alpha + \frac{c}{\alpha} \left(t + \frac{1}{\Gamma(\alpha)} \right)^\alpha.$$

5. Concluding Remarks

We have applied a new approach of the Kudryashov method to the time-fractional fifth-order Sawada-Kotera equation and the $(4 + 1)$ -dimensional space-time fractional Fokas equation which arise in mathematical physics. The wave transformations applied with the help of beta derivative definitions and the Q function included in the algorithm facilitated the computation of the solutions. The general solutions for the time-fractional fifth-order Sawada-Kotera equation and the $(4 + 1)$ -dimensional space-time fractional Fokas equation have been pointed out as polynomials of the logistic function, which in turn are solutions of the Riccati equation. Finally, some new exact solutions in the form of exponential functions for given equations are established. We have also presented the numerical simulations for equations thanks to three dimensional plots. Therefore, we conclude that this method may have general applications. As comparing the other methods, the advantage of this approach is that the form of function is not used at the calculation. This gives us not only ease of calculation, but also the opportunity to obtain new solutions. However, it should not be overlooked that this new method is more suitable for nonlinear equations with even-order derivatives. Hence, one can conclude that the method can be applied to many fractional partial differential equations.

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