# Dynamics of the capillary rise in tilted Taylor-Hauksbee cells 

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In this work, we theoretically and experimentally study the issue of the spontaneous capillary rise of a viscous liquid in wedge-shaped tilted cells, with very short angles of aperture, $\alpha$. We provide the equilibrium profiles $y_{s_{e}}$ and, by means of the Reynolds lubrication equations, we find the time-dependent profiles and the dynamic evolution of the meniscus close to the edge of the wedge, as a function of time, which follow power laws of the form $y_{s} \sim t^{1 / 3}$. Experiments performed at various inclinations are consistent with our theoretical results.

Keywords: Capillary rise; hydrostatics; lubrication flows.

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## 1. Introduction

The spontaneous capillary rise of a viscous liquid within a vertical wedge-shaped cell, made out of two flat plates touching at an edge and having a very short angle between them, was experimentally studied for the first time by Brook Taylor [1] and Francis Hauksbee [2] in 1712, showing the existence of the capillary action; as well as the formation of equilibrium profiles, shaped as rectangular hyperbolas. We will refer to this configuration as the Taylor-Hauksbee (T-H) cell.

Surprisingly, such configuration has been very helpful to understand the capillary rise in a myriad of natural and manufactured functional surfaces having open, nano or micro Vgrooves. For instance, a study of the peristome surface of Nepenthes alata (a carnivorous pitcher plant) showed that the plant has taken full advantage of the corner geometry to apply the straightforwardional control of the liquid flow [3-5]. Natural functional surfaces like peristome surface give inspiration for designing and fabricating functional surfaces and materials with wide applications including water transport for agricultural drip irrigation over long distances, controllable self-lubrication and smart and controllable microfluidic devices [5], to name a few. Implementations of V-grooves in devices at a larger scale has been done to improve the heat transfer capacity of heat pipes [6] as well as open capillary siphons [7]. Coincidently, it has recently been proposed that capillary corner flow is also an important transport mechanism during the spreading of viruses and bacteria $[8,9]$.

From a theoretical point of view, Tang et al. [10] studied the capillary rise along the angular corner formed by the contact of a thin rod inside a larger vertical tube (whose diameter is smaller than the capillary length $a=(\sigma / \rho g)^{1 / 2}$, where $\sigma$ is the surface tension, $\rho$ is the density of the liquid and $g$ is the acceleration of gravity). They found that at large time scales the elevation of the meniscus at the edge of the groove, $h$, follows a slow motion characterized by a power law of the form $h \sim t^{1 / 3}$. Subsequently, the same power law was found in theoretical studies for capillary rise in linear [11-13] and nonlinear corner-like grooves [13, 14], having a small opening angle. In all these cases, apparently there are no equilibrium heights for the menisci rise $[15,16]$.

In a theoretical treatment of tilted T-H cells, carried out by Tian et al. [17], the capillary rise and the time evolution of the free surface, far from the horizontal surface of the liquid, were studied. Such study was motivated since the microstructures on the peristome surface resembles the geometry of intersecting plates but with the arista being curved and tilted. Based on the Onsager principle, i.e., a method to find the minimum of the Rayleighian, which is the summation of the change rate of the free energy of the liquid and the dissipation function, Tian et al obtained that the rise of the meniscus front also obeys, at large times, the $t^{1 / 3}$ power law.

Motivated by the new applications, in the present work we will analyze the issue of the dynamic evolution of the free surface within a tilted Taylor-Hauksbee cell by using the lubrication theory approximation, which was previously used to model the capillary rise in vertical T-H cells [11]. Now, following this approach we formulate the Reynolds lubrica-
tion equations, in the tilted system, which allows us to obtain the simplest form the problem for the dynamic evolution of the free surface in the tilted system.

Our treatment, as backed by experiments, will provide evidence that the capillary rise of the meniscus, close to the sharp edge, is faster for larger inclinations and that it also follows the power law $t^{1 / 3}$ for large time periods.

To reach our goal, in the next Section we describe the problem and we obtain analytically the equilibrium surfaces in terms of the rotated and un rotated coordinate systems. Later on, in Sec. 3, we use said coordinate system in the lubrication theory to obtain the simplest set of equations possible. In Sec. 4, we performed a series of experiments, using glassmade tilted T-H cells and silicone oil, to obtain the dynamic evolution of the free surfaces before attaining the equilibrium surfaces. The physical parameters governing the experiments will be introduced in the numerical treatment to do a straightforward comparison between the theoretical and experimental profiles and to show that our theoretical approach is suitable. Finally, in Sec. 5, we present the main conclusions for this work.

## 2. Equilibrium profiles

### 2.1. The physical problem

The tilted T-H cell is formed when two plates touch at the edge and make a very short aperture angle $\alpha(\alpha \ll 1)$, meanwhile, the whole cell is tilted at a clockwise angle, $\beta$, with respect to the vertical, see Fig. 1a). If the cell is brought in


Figure 1. a) Depiction of a Taylor-Hauksbee cell, tilted at a clockwise angle $\beta$ with respect to the vertical, and with a small aperture angle $\alpha$. In this case the horizontal level of the liquid meets the lower corner on the left had side of the cell. b) Schematic indicating the two-dimensional Cartesian coordinate systems ( $x^{\prime}, y^{\prime}$ ) and ( $x, y$ ), with a common origin. The equilibrium free surface is $y_{s_{e}}(x)$, in the tilted system. c) Schematic of the arc lenght, $\alpha x$, of the channel at the distance $x$ from the intersection edge ( $x=0$ ) with the contact angle, $\theta$, also being shown.
to contact with a viscous liquid of dynamic viscosity $\mu$ and it wets the interior surfaces of the plates, it will rises into the initially empty wedge-shaped gap. From a theoretical point of view, it is possible to describe the capillary rise of the liquid by taking into account that under the gravity action, the liquid's horizontal level is at $y^{\prime}=0$, alluding to the unrotated two-dimensional Cartesian coordinate system ( $x^{\prime}, y^{\prime}$ ), where the $x^{\prime}$-axis is parallel to the horizontal level, see Fig. 1b).

If liquid wets the plates, the contact angle $\theta$ obeys that $\theta<\pi / 2$, see Fig. 1c). As depicted in Fig. 1b), the profile of the free surface of the liquid in the tilted cell could also be described with the rotated Cartesian coordinate system ( $x$, $y$ ), whose $y$-axis is attached to the arista of the cell. Notice that the rotated and the unrotated coordinate systems have the same origin. Our aim here is to analytically describe the free surface profiles in both coordinate system, which will also be useful in the formulation of the capillary rise equations, derived from the lubrication theory.

### 2.2. Cartesian coordinate systems

The actual equilibrium profiles evolve within the tilted T-H cells driven by the capillary action and limited by gravity. Therefore, the natural description of these profiles must carried out at the tilted (rotated) coordinate system $(x, y)$. However, mathematically, it is possible to describe such profiles at the un tilted system $\left(x^{\prime}, y^{\prime}\right)$, but in this latest coordinate system the profiles may not be one-to-one (injective) functions.

If we locate the point $P$ in the unrotated coordinate system, said point has the coordinates $\left(x^{\prime}, y^{\prime}\right)$, as seen in Fig. 1 b ), but the same point $P$ in the system ( $x, y$ ), rotated an angle $\beta$, is given by the transformation

$$
\begin{align*}
& x=x^{\prime} \cos \beta-y^{\prime} \sin \beta  \tag{1}\\
& y=x^{\prime} \sin \beta+y^{\prime} \cos \beta \tag{2}
\end{align*}
$$

and the location of the point $P$ at the unrotated system, in terms of the coordinates $(x, y)$, is given by

$$
\begin{align*}
& x^{\prime}=x \cos \beta+y \sin \beta  \tag{3}\\
& y^{\prime}=-x \sin \beta+y \cos \beta \tag{4}
\end{align*}
$$

These transformations will become useful in the description of the equilibrium profiles, and in the capillary rise theory formulation.

### 2.3. The equilibrium profiles in the tilted system

Given the coordinate systems, it is straightforward to obtain the equilibrium free surface in the coordinate system $(x, y)$, given that in said system, the curvature radius at the point $P$ takes the value $\alpha x / 2 \cos \theta$, since said point is at a distance $x$ from the edge. There, the pressure jump across the surface is approximately $\Delta p_{s}=2 \sigma \cos \theta / \alpha x[11,18]$. At the same point, the hydrostatic pressure is $\Delta p_{s}=\rho g y^{\prime}$, measured in the unrotated coordinate system, meanwhile said pressure has
the form $\Delta p_{s}=\rho g\left(y_{s_{e}} \cos \beta-x \sin \beta\right)$, in terms of the coordinates of the rotated system (where the Eq. (4) was used). The balance of both pressure values yields the equations for the equilibrium surfaces, in the tilted system,

$$
\begin{equation*}
y_{s_{e}}(x)=\frac{2 \sigma \cos \theta}{\rho g \alpha x \cos \beta}+x \tan \beta \tag{5}
\end{equation*}
$$

notice that if $\beta=0$ in Eq. (5), the classical equilibrium surface is obtained [11]

$$
\begin{equation*}
y_{s_{e}}(x)=\frac{2 \sigma \cos \theta}{\rho g \alpha x} \tag{6}
\end{equation*}
$$

formally, from Eq. (5) it is clear that the equilibrium height of the liquid at the edge (when $x \rightarrow 0$ ), for any angle between $0 \leq \beta<\pi / 2$, goes to infinity $\left(\lim _{x \rightarrow 0} y_{s e} \rightarrow \infty\right)$, however the rest of the equilibrium profile takes finite heights.

On the other hand, the equilibrium surfaces in the tilted system have their minima (when $d y_{s_{e}} / d x=0$ ) at

$$
\begin{equation*}
x_{\min }=\left(\frac{2 \sigma \cos \theta}{\rho g \alpha \sin \beta}\right)^{1 / 2} \tag{7}
\end{equation*}
$$

it is clear that the position of $x_{\min }$ will be located at infinity if $\beta \rightarrow 0$. Similarly, the corresponding value of $y_{\min }$, at $x_{\min }$, is given for each specific inclination $\beta$, as

$$
\begin{equation*}
y_{\min }=\left(\frac{2 \sigma \cos \theta}{\rho g \alpha}\right)^{1 / 2} \frac{2 \sin ^{1 / 2} \beta}{\cos \beta} \tag{8}
\end{equation*}
$$

it is clear that the position of $y_{\min }$ goes to infinity if $\beta \rightarrow \pi / 2$.
In experiments discussed later on the work fluid was silicone oil, a nonvolatile liquid at room temperature; which has the following nominal values: dynamic viscosity $\mu=0.1$ Pa s, surface tension $\sigma=0.0215 \mathrm{~N} / \mathrm{m}$ and density $\rho=$ $971 \mathrm{Kg} / \mathrm{m}^{3}$. The average contact angle, measured using the static sessile drop method, for silicone oil over flat glass was


Figure 2. Plot of the equilibrium profiles (Eq. (5)), from the perspective of the rotated coordinate system $(x, y)$, the aperture angle being $\alpha=0.0166 \mathrm{rad}\left(0.95^{\circ}\right)$. The dashed curves belong to the tilt angles: black $\beta=0$, red $\beta=0.2618\left(15^{\circ}\right)$, green $\beta=0.5236$ $\left(30^{\circ}\right)$, blue $\beta=0.7854\left(45^{\circ}\right)$ and magenta $\beta=1.0472\left(60^{\circ}\right)$.


Figure 3. Plot of the change of $x_{\text {min }}$ as a function of the tilt angle $\beta$ (Eq. (7)). In the inset a similar plot for $y_{\min }$ (Eq. (8)), is presented.
found to be $\theta=0.122 \pm 0.006 \mathrm{rad}\left(7^{\circ}\right)$ at room temperature $T_{\text {room }}=296.15 \mathrm{~K}$. The plots in Fig. 2 were computed using previously available data and the aperture angle was taken to be $\alpha=0.016 \mathrm{rad}\left(0.95^{\circ}\right)$. We show several plots of the equilibrium profiles (Eq. (5)), in which the positions of their minima in the rotated coordinate system $(x, y)$ can be appreciated for several tilt angles $\beta$.

Employing the same data as in Fig. 2, the graphical behavior of the positions of $x_{\text {min }}$ and $y_{\text {min }}$, for a continuum of values of $\beta$ are given in Fig. 3, where the aforementioned observations of the locations of the minima, are confirmed.

### 2.4. Profiles from an unrotated coordinate system

It has been mentioned that it is also possible to plot the equilibrium profiles formed in the tilted cell, for the unrotated system $\left(x^{\prime}, y^{\prime}\right)$. The equilibrium profiles in the unrotated coordinate system are obtained by introducing Eq. (5) into Eqs. (3)-(4), yielding

$$
\begin{equation*}
y_{s e}^{\prime}=\frac{x^{\prime} \pm \sqrt{x^{\prime 2}-\frac{8 \sigma \cos \theta}{\rho g \alpha} \frac{\tan \beta}{\cos \beta}}}{2 \tan \beta} . \tag{9}
\end{equation*}
$$

If we choose the plus sign in Eq. (9), we find for large values of $x^{\prime}$ that

$$
\begin{equation*}
y_{s e}^{\prime} \approx \frac{x^{\prime}}{\tan \beta}-\frac{2 \sigma \cos \theta}{\rho g \alpha} \frac{1}{x^{\prime} \cos \beta} \tag{10}
\end{equation*}
$$

meanwhile, if the sign minus it is chosen, we find that

$$
\begin{equation*}
y_{s e}^{\prime} \approx \frac{2 \sigma \cos \theta}{\rho g \alpha} \frac{1}{x^{\prime} \cos \beta} \tag{11}
\end{equation*}
$$

In Fig. 4 we plot the equilibrium profiles in the unrotated coordinates $\left(x^{\prime}, y_{s e}^{\prime}\right)$, using Eq. (9) for the same liquid and inclination and aperture angles given in Fig. 2.


Figure 4. Plots of the equilibrium profiles (Eq.(9)) in the ( $x^{\prime}, y^{\prime}$ ) coordinate system. The tilt and aperture angles are the same as those in Fig. 2.

In plots of Fig. 4 the upper part of each profile is given by Eq. (10) and the respective lower part of each profile is given by Eq. (11). Some experimental profiles will be shown later on.

## 3. Capillary rise: use of the lubrication theory

The film flow due to capillary rise in T-H cells occurs at small Reynolds numbers [11]. Therefore, we can use the Reynolds' lubrication theory to compute the distribution of the modified pressure $P$ and the rise of the meniscus. In the unrotated system said a pressure is $P=p+\rho g y^{\prime}$, where $p$ is the pressure of the liquid referred to the pressure of the surrounding gas $\left(p_{a}\right)$ and $y^{\prime}$ is the vertical distance from the the horizontal level of the outer liquid. By using Eq. (4) in the aforementioned modified pressure, it is straightforward to find that the form of this pressure in the tilted system is $P=p+\rho g(y \cos \beta-x \sin \beta)$.

The lubrication theory [11, 19], uses the width-averaged flux per unit length given by $\mathbf{q}=\left(q_{x}, q_{y}\right)$ where $q_{x}=$ $-(\alpha x)^{3}(\partial P / \partial x) / 12 \mu$ and $q_{y}=-(\alpha x)^{3}(\partial P / \partial y) / 12 \mu$. Therefore, the mass conservation equation $\partial q_{x} / \partial x+$ $\partial q_{y} / \partial y=0$ yields the Reynolds equation for the modified pressure as

$$
\begin{align*}
& \frac{\partial}{\partial x}\left(x^{3} \frac{\partial P}{\partial x}\right)+x^{3} \frac{\partial^{2} P}{\partial y^{2}}=0 \\
& \quad \text { in } \quad 0<y<y_{s}(x, t), \quad x>0 \tag{12}
\end{align*}
$$

here, $y_{s}$ is the free surface in the tilted system. The modified pressure obeys the equation

$$
\begin{align*}
P & =-\frac{2 \sigma \cos \theta}{\alpha x}+\rho g\left(y_{s} \cos \beta-x \sin \beta\right) \\
\text { at } \quad y & =y_{s}(x, t) \tag{13}
\end{align*}
$$

which expresses that said pressure at the free surface is the sum of the capillary depression $-\Delta p_{s}$, previously mentioned, plus the hydrostatic term.

At the evolving free surface $y_{s}$, the kinematic condition (which states that the fluid does not cross the free surface) is given by $-(\partial f / \partial t) \alpha x=\mathbf{q} \cdot \nabla f \quad$ [18]; where $f=$ $y-y_{s}(x, t)=0$, is the free surface equation. Then, the kinematic condition can be written as

$$
\begin{align*}
& \frac{\partial y_{s}}{\partial t}+\frac{(\alpha x)^{2}}{12 \mu}\left(\frac{\partial P}{\partial y}-\frac{\partial P}{\partial x} \frac{\partial y_{s}}{\partial x}\right)=0 \\
& \text { at } \quad y=y_{s}(x, t) \tag{14}
\end{align*}
$$

Equations (12), (13) and (14) will be solved under the following boundary conditions

$$
\begin{align*}
q_{x} & =-\frac{(\alpha x)^{3}}{12 \mu} \quad \frac{\partial P}{\partial x} \rightarrow 0 \quad \text { if } \quad x \rightarrow 0  \tag{15}\\
P & =0 \quad \text { at } \quad y=0  \tag{16}\\
y_{s} & \rightarrow x \tan \beta \quad \text { for } \quad x \rightarrow \infty \tag{17}
\end{align*}
$$

The condition (15) imposes that the flux through the edge of the wedge $(x=0)$ is zero, Eq. (16) expresses that the modified pressure at the lower edge of the plates $(y=0$ if the lower corner $x=y=0$ is at the level of the outer liquid, as in Fig. 1) is also zero and finally, Eq. (17) states that far from the arista the free surface is very close to the horizontal level of the liquid. The problem described by Eqs. (12)(14) will be solved numerically for a given initial condition $y_{s}(x, 0)=y_{s_{i}}(x)$.

The system of partial differential equations subject to the boundary conditions was solved using an implicit finite differences discretization. A careful analysis of the solutions as functions of the spatial and temporal in-homogeneous meshes allowed us to find out that a $50 \times 50$ mesh is adequate to achieve an accurate solution. The numerical time step was variable; in the first stages of the phenomenon the time step was about $10^{-9}$ and it was exponentially increased as the phenomenon evolved. Typical calculations were made for a total of 20000 time steps.

Incidentally, following the same approach as used in Ref. [11], but now for the tilted system, we find that the asymptotic self-similar solution for the meniscus of the thin layer close to the edge $(x \rightarrow 0)$, at large values of the time $t$, yields the elevation of the meniscus at the edge as $y_{s} \approx A(t / \cos \beta)^{1 / 3}$ with $A=1.25(\sigma \cos \theta)^{2 / 3} /(\mu \rho g)^{1 / 3}$ [20].

## 4. Experiments

To compare the numerical dynamic profiles with those obtained experimentally, we performed a series of experiments with silicone oil. Ad hoc T-H cells having different inclinations of the arista were made with flat glass plates ( 3 mm thick) of different sizes. Wedges with different short angles were made by keeping the plates in contact along the arista and by fitting, between the glass plates, a thin metallic sheet,


Figure 5. Pictures of the equilibrium profiles, indicated by dashed curves, at tilt angles: a) $\beta=0 \mathrm{rad}$, b) $\beta=0.524 \pm 0.002 \mathrm{rad}\left(30^{\circ}\right)$ and c) $\beta=1.047 \pm 0.002 \mathrm{rad}\left(60^{\circ}\right)$; where the mean aperture angle was $\alpha=0.011 \mathrm{rad}$. Photographs were taken approximately one day after the start up of the capillary rise. The scale on the ruler is in cm .
parallel to the arista, at a certain distance from it. Special care was taken to avoid any contact of the metallic sheet with the silicone oil during the profile formation. Each angle $\alpha$, of a given cell, was computed through the measurement of the narrow space between the plates, at the rim opposite to the edge. On the other hand, the tilt angle $\beta$ was measured using a digital clinometer (accuracy $\pm 0.1^{\circ}$ ).

In Fig. 5 we present pictures of the equilibrium profiles for three representative cases with inclination angles: 5a) $\beta=0 \pm 0.002 \mathrm{rad}, 5 \mathrm{~b}) \beta=0.524 \pm 0.002 \mathrm{rad}\left(30^{\circ}\right)$ and 5c) $\beta=1.047 \pm 0.002 \mathrm{rad}\left(60^{\circ}\right)$. In these experiments the mean aperture was $\alpha=0.012$ rad and the equilibrium pro-
files were photographed in all cases, one day after the T-H cells were brought into contact with the silicone oil.

Due to our assembly procedure of the T-H cells, the aperture angles $\alpha$ were different for every experiment. In Fig. 6 we show the plot of several instantaneous profiles in a cell having the same tilt angles as in Fig. 5, but the aperture angles were: 6a) $\alpha=0.019 \pm 0.0001 \mathrm{rad}\left(1.0^{\circ}\right)$, Fig. 6b) $\alpha=$ $0.008 \pm 0.0004 \mathrm{rad}\left(0.45^{\circ}\right)$ and Fig. 6c) $\alpha=0.010 \pm 0.0005$ $\operatorname{rad}\left(0.63^{\circ}\right)$. It is evident that the scales in the plots were located on the unrotated coordinates and, as a reference, the black-color solid lines on the left side represent the edges of the cells ( $y$-axis). In Fig. 6 symbols depict experimental data and the dashed curves that closely fit them represent the numerically computed profiles, obtained from the numerical solutions of the problem posed by Eqs. (12)-(17).

From comparisons between the experimental and numerical profiles, given in Fig. 6, we can establish that the numerical computations closely predict the evolution towards the equilibrium state of the free surfaces. The black-color dashed curves correspond to the numerical equilibrium profiles, which were obtained as in Fig. 5, i.e., one day after of the start-up of the capillary rise, having not observed any change of said equilibrium profiles. The shapes of the equilibrium profiles can also be obtained with Eq. (5) and none appreciable difference was found between the analytic and numerical profiles.

The location of the instantaneous height $y_{s}(t)$, for each tilt angle, is shown in Fig. 7. The numerical computations closely fit the experimental data. It can be noted that all data fit power laws of the form $y_{s} \sim t^{1 / 3}$; the green curve was drawn as a visual guide of the power law $y_{s} \sim t^{1 / 3}$. From the plots in Fig. 7 we can also appreciate that the aperture and inclination angles determine substantial changes in the kinetics of the capillary rise.



FIGURE 6. Numerically computed and experimentally obtained profiles for different time lapses during the capillary rise. The tilt angles are: a) $\beta=0 \mathrm{rad}$, b) $\beta=0.524 \pm 0.002 \mathrm{rad}\left(30^{\circ}\right)$ and c) $\beta=1.047 \pm 0.002 \mathrm{rad}\left(60^{\circ}\right)$. The aperture angles for each inclination are specified in the main text. The dashed curves represent the numerical solutions of Eqs. (12)-(17). Error bars and symbols are of the same size.


Figure 7. Plots of the time dependent heights $y_{s}(t)$, measured at the edges, for the three inclinations used in Fig. 6. The black, blue and magenta curves correspond to the numerical solutions of Eqs. (12)-(14) for various inclinations. Symbols in this plot match those for experimental data in Fig. 6. The green curve represents the power law $y_{s} \sim t^{1 / 3}$. For the three different tilt angles, power laws of this type closely fit data at large times. Error bars corresponds to a $4 \%$ error.

## 5. Conclusions

In this work, we have theoretically and experimentally analyzed the problem of the spontaneous capillary rise of vis-
cous liquids in tilted Taylor-Hauskbee cells, with a particular case being the rise in vertical cells. In the theoretical treatment we used the rotation of coordinates to describe in a straightforward manner the equilibrium profiles and the dynamic evolution of the free surfaces, following the application of the Reynolds lubrication equations. We found selfsimilar asymptotic solutions for the meniscus elevation, at large values of time, which follows power laws of the form $y_{s} \sim t^{1 / 3}$. The complete set of equations of the problem, given by Eqs. (12)-(14), were also solved numerically, and these solutions allowed us to compute the instantaneous profiles for three inclination angles and to validate that at large values of time the meniscus elevation, close to the edge, follows the power laws $y_{s} \sim t^{1 / 3}$. Experiments with $\mathrm{Ad} H o c$ T-H cells for three different tilt angles, $\beta$, and different aperture angles, $\alpha$, back our numerical results. Finally, in the context of applications, given that the capillary flow in tilted corners is faster than in vertical standing corners, crucial phenomena such as the transport of viruses and bacteria will be substantially modified.

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20. A thin layer of liquid develops around the edge of the wedge for large times, where the solution tends to become self-similar. Looking for the surface of this layer in the form $x=G(y, t)$, in terms of the dimensionless variables $x, y$ and $t$ of [11], it can be seen that $G=g(\eta) / t^{1 / 3}$ with $\eta=y / t^{1 / 3}$, and $g(\eta)$ satisfies $(1 / 4) g g^{\prime \prime}+\left((1 / 2) g^{\prime 2} \cos \beta\right) g^{\prime}+(1 / 3)(\eta g)^{\prime}=0$ with the boundary conditions $g \rightarrow 1 /(\eta \cos \beta)$ for $\eta \rightarrow 0$ and $g=(2 / 3) \eta_{0}\left(\eta_{0}-\eta\right)$ for $\eta \rightarrow \eta_{0}$, where $\eta_{0}$ is to be found. The problem can be reduced to that for a vertical wedge ( $\beta=0$ ) using a scale transformation. Its numerical solution determines $\eta_{0} \approx 1.81 / \cos ^{1 / 3} \beta$, so that the dimensionless elevation of the meniscus at the edge is $y \approx 1.81(t / \cos \beta)^{1 / 3}$ for large times.
