

FEW-NUCLEON REACTIONS WITH CENTRAL FORCES

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RESUMEN

The three-channel reactions for $D(A,Z)$, with $A \leq 4$, have been formulated by using the resonating group method. The potential used is a two-body central interaction with exchange dependence and Gaussian shape. The wave functions for the ground state of the nuclei are also Gaussian (double Gaussian for deuterons and single Gaussian for the other nuclei), the parameters being determined by a variational method to fit the binding energies.

Coupled integro-differential equations have been derived for each value of the total spin and angular momentum of the corresponding system. General formulae are given for the different terms of these equations.

I INTRODUCTION

A general form of a collective model was developed in a fundamental paper by J.A. Wheeler in 1937.¹

In this theory, any state of a nucleus is regarded as a superposition of all possible kinds of nucleon clusters, continually broken and re-formed in new ways, the interchange of neutrons and protons between the groups being largely responsible for the intergroup forces. Such a state is called by Wheeler a "resonating group structure". To make the calculation feasible, no more than two clusters are considered, and the intergroup separation variable \vec{r} (joining the centers of mass of the two clusters) is the main one of the problem, the scattering function being $F(\vec{r})$. After an exchange of nucleons between the clusters, \vec{r} becomes \vec{r}' . It can then be shown that for any type of interaction we get an equation of the form

$$\left(\frac{\hbar^2}{2\mu} \nabla_r^2 + E_{inc} \right) F(\vec{r}) = U(r) F(\vec{r}) + \int K(\vec{r}, \vec{r}') F(\vec{r}') d\vec{r}'. \quad (1)$$

Because of the principle of conservation of energy, $K(\vec{r}, \vec{r}')$ is symmetric in \vec{r} and \vec{r}' .

The three-nucleon problem (n-d scattering) was tackled first by Buckingham and Massey in 1941², using a central potential of exponential shape and the Massey and Mohr wave function³ for the ground state of the deuteron.

Since then, and also in this paper, Gaussian have been preferred both for the potential shape and for the nuclear wave function because the analysis is easier and can be carried out further. But even when the Gaussian shape is used, the solution of eq. (1) still requires the help of a powerful computer to tabulate the kernels and to solve eq. (1) using finite-difference approximations⁴. Both programs have been written for the Ferranti Mercury digital computer by Dr. Philip G. Burke, and are now available at London University Computer Unit⁵.

The work presented here is half way between the fundamental Wheeler paper on resonating group structure and Burke's programs for tabulating kernels and solving the equations.

The reactions involved in the following scheme are considered here.

$$\left(\begin{array}{ccc} D(A,Z) \rightarrow D(A,Z) & D(A,Z) \rightarrow n(A+1, Z+1) & D(A,Z) \rightarrow p(A+1, Z) \\ n(A+1, Z+1) \rightarrow D(A,Z) & n(A+1, Z+1) \rightarrow n(A+1, Z+1) & n(A+1, Z+1) \rightarrow p(A+1, Z) \\ p(A+1, Z) \rightarrow D(A,Z) & p(A+1, Z) \rightarrow n(A+1, Z+1) & p(A+1, Z) \rightarrow p(A+1, Z) \end{array} \right)$$

This is written in abbreviated form as

$$\begin{pmatrix} AA & AB & AC \\ BA & BB & BC \\ CA & CB & CC \end{pmatrix}$$

For $A = 2$ we have the full three-channel $d-d$ reaction⁶; for $A = 3$ we have the two-channel $d-t$ reactions⁷ or $d-He^3$ reactions; for $A = 4$ we have the single-channel $d-He^4$ elastic scattering.

The minor of AA of the type $N(A,Z)$ (N being a nucleon, either a neutron, n or proton, p), and most of the possible cases have already been published. The $n-d$ case of course, has been extensively studied; the Gaussian formulation with central forces of interest in connection with this paper has been carried out separately for $n-d^8$, $n-He^3$ and $n-T^9$, $N-He^4$,¹⁰ and finally the two-channel $n-He^3$ case¹¹

In each of the above papers is a formulation corresponding to the reaction studied; all the formulations published (or to be published) can be found herein, so that Wheeler's model appears with full effect namely, covering a very large quantity of experimental data with only three parameters: V_0 (potential depth), $\rho_0 = 1/\sqrt{\mu}$ (range of the nuclear forces), and the type of exchange. However, one must keep in mind that the formulation is only the minor part of these problems, the far greater one being to get out numerical results, and in that respect the machine programs are much more valuable.

The limitation $A \leq 4$ is due to the symmetry property of the ground-state nuclear wave functions, namely factorization of spin and space part with invariance of the space part under any permutation of the nucleons inside the nucleus. This important property allows for a relabeling of the nucleons, which considerably simplifies the analysis.

Among the possible types of functions consistent with that property, Gaussian functions have been preferred. We take, for the potential shape, $V(r) = V_0 e^{-\mu r^2}$; for the deuteron wave function,

$$\phi(A+1, A+2) = \phi(\rho_1) = \frac{1}{N_D} [\exp(-\alpha \rho_1^2) + c \exp(-\beta \rho_1^2)] ;$$

and for any other nuclei,

$$\phi(A,Z) = \phi(1,2,\dots,A) = \frac{1}{N_A} \exp \left[- (\lambda/2) \sum (ij)^2 \right]$$

As we have $A \leq 4$, we can denote protons by even numbers and neutrons by odd numbers. Also we assume 1 and $A+1$ to be of the same nature, as well as 2 and $A+2$.

From the form of $\phi(A,Z)$ it is obvious that AC can be deduced from AB , and similarly BB and CC from BC , by appropriate changes of λ .

Finally, owing to the symmetry property of the scattering matrix, we have $BA = (AB)^\dagger$, $CA = (AC)^\dagger$, $CB = (BC)^\dagger$, and we need to consider only the three terms

$$AA, AB, BC.$$

In the minor of AA , the nucleus involved contains $A+1$ nucleons; when dealing with it, to simplify the formulae, we write only A , so that we have at once the formulae ready for the two channels $N(A,Z)$. The method is detailed in that case, and only tables are given for AA and AB and for BC .

Chapter II of this paper defines the central two-body interaction used in the formulation, and deals with the space-part wave function of the nuclei (A,Z) . Chapter III gives the wave function, written according to the resonating-group-structure method, and the corresponding equations that the wave function must satisfy. Chapter IV is a brief review of the method for getting the cross sections; this topic is dealt with in detail in other papers^{12, 13}.

In UCRL 9674 are given some details of the algebra involved in the calculations.

II. The Two-Body Potential and the Nuclear Wave Functions

1.- The Exchange-Dependent Two-Body Potential

The potential used is a central two-body potential with Gaussian shape and

exchange dependence. It can be written equally well in two forms, and the connection between these forms is reviewed here.

The interaction between two nucleons can be written (using the same shape for all exchange potentials) as

$$U(r_{ij}) = (w W_{ij} + m M_{ij} + b B_{ij} + b H_{ij}) V(r_{ij}) + \epsilon_{ij} \cdot \frac{e^2}{r_{ij}},$$

where $\epsilon_{ij} = 1$ if i and j are protons, and zero otherwise,

$$r_{ij} = |\vec{r}_i - \vec{r}_j|$$

W_{ij} is an identity operator, and M_{ij} , B_{ij} , H_{ij} are the usual Majorana, Bartlett, and Heisenberg operators exchanging space, spin, and spin-and-space co-ordinates of particles i and j such that $HBM\psi = W\psi = \psi$.

According to the Pauli principle, the total wave function must be totally antisymmetric in space, spin, and isotopic spin so that, since $H' = \frac{1}{2}(1 + \vec{\tau}_i \cdot \vec{\tau}_j)$ is the operator exchanging the isotopic spin, we have $H'BM\psi = -\psi$. Consequently we have $H' = -H$, and $H_{ij} = -\frac{1}{2}(1 + \vec{\tau}_i \cdot \vec{\tau}_j)$. As $B_{ij} = \frac{1}{2}(1 + \vec{\sigma}_i \cdot \vec{\sigma}_j)$, we deduce $M_{ij} = -\frac{1}{4}(1 + \vec{\sigma}_i \cdot \vec{\sigma}_j)(1 + \vec{\tau}_i \cdot \vec{\tau}_j)$. Either from their very definition or from the above expressions, we deduce the following multiplication table:

	W_{ij}	M_{ij}	B_{ij}	H_{ij}
W_{ij}	W_{ij}	M_{ij}	B_{ij}	H_{ij}
M_{ij}	M_{ij}	W_{ij}	H_{ij}	B_{ij}
B_{ij}	B_{ij}	H_{ij}	W_{ij}	M_{ij}
H_{ij}	H_{ij}	B_{ij}	M_{ij}	W_{ij}

The constants w , m , b , and b determine the relative importance of each type of exchange; they are chosen according to the different theories of nuclear forces,

and it is hoped that the comparison of the final results with the experimental data lead to a reasonable choice.

Let us write $V(r_{ij}) = V_0 f(\mu, r_{ij})$, where V_0 and μ give the depth and the range of this well, and

$$\psi_{ij} = \sum_{l,s} \phi_l(r_{ij}) Y_{l,m}(\theta, \phi) \sigma_s(ij)$$

is a wave function for the two nucleons i and j .

Then $V(r_{ij})$ acting on ψ_{ij} will give an effective potential $\frac{2S+1}{2T+1} V_0 (-1)^l$, such that

$$\frac{2S+1}{2T+1} V_0 (-1)^l = [w + (-1)^l m + (-1)^{s+1} b + (-1)^{l+s+1} b] V_0 f(\mu, r_{ij}).$$

We take $w + m + b + b = 1$, so that V_0 is the depth of the well of the deuteron in the 3S state. Also,

$$w + m - b - b = x$$

is the ratio of the 1S to 3S interaction.

The value of x is usually taken to be 0.6.¹⁴

We have

$$w + m = \frac{1+x}{2} = \frac{{}^3V + {}^1V}{2({}^3V)} = 1 - g;$$

$$b + b = \frac{1-x}{2} = \frac{{}^3V - {}^1V}{2({}^3V)} = g.$$

Using the previous definitions of W_{ij} , M_{ij} , B_{ij} , and H_{ij} , we can write the nuclear interaction.

$$U(r_{ij}) = [w + m M_{ij} + b \left(\frac{1 + \vec{\sigma}_i \cdot \vec{\sigma}_j}{2} \right) + b M_{ij} \left(\frac{1 + \vec{\sigma}_i \cdot \vec{\sigma}_j}{2} \right)] V(r_{ij}).$$

As M_{ij} had no effect on even states, we have, for the states of even parity only,

$$\left[w + m + \frac{b}{2} + \frac{b}{2} + \left(\frac{b+b}{2}\right) \vec{\sigma}_i \cdot \vec{\sigma}_j \right] V(r_{ij}) = \left[1 - \frac{1}{2}g + \frac{1}{2}g (\vec{\sigma}_i \cdot \vec{\sigma}_j) \right] V(r_{ij}).$$

The potential for states of odd parity is suggested by meson theory:

(a) Ordinary forces or neutral meson theory:

$$V_{\text{odd}} = V_{\text{even}}, \text{ i.e., } m = b = 0, w = 1/2(1+x), b = 1/2(1-x).$$

(b) Exchange forces or charged-meson theory:

$$V_{\text{odd}} = (-1)^l V_{\text{even}}, \text{ i.e., } w = b = 0, m = 1/2(1+x), b = 1/2(1-x).$$

(c) Symmetric forces or *M H W B*:

$$V_{\text{odd}} = -1/3 (\vec{\tau}_i \cdot \vec{\tau}_j) (\vec{\sigma}_i \cdot \vec{\sigma}_j)_{\text{even}}, \text{ i.e., } {}^3V_{\text{odd}} = -1/3 {}^3V_{\text{even}}$$

$$\text{and } {}^1V_{\text{odd}} = -3 {}^1V_{\text{even}},$$

or

$$m = 2b = (1/3)(1+3x), \quad b = 2w = (1/3)(1-3x).$$

(because here $\vec{\tau}_i \cdot \vec{\tau}_j$ goes as $\vec{\sigma}_i \cdot \vec{\sigma}_j$, and $\vec{\sigma}_i \cdot \vec{\sigma}_j = +1$ for triplet states and $\vec{\sigma}_i \cdot \vec{\sigma}_j = -3$ for singlet states).

(d) Serber empirical forces:

$$V_{\text{odd}} = 0, \quad w = m = (1/4)(1+x), \quad b = b = (1/4)(1-x).$$

(e) Biel's force, a mixture of Serber and symmetrical exchange (which has given good results for the binding energy of the first 4n nuclei and the α - α scattering):

$$V_{\text{Biel}} = (1/3) V_{\text{sym}} + (2/3) V_{\text{Serber}}, w = b = 5/18, \quad b = (5/18) - (x/2),$$

$$m = 5/18 + x/2$$

That the deuteron has a quadrupole moment implies that the nuclear force is not merely a central one.

However, so that preliminary results may be obtained in a reasonable time, this work does not include a tensor force or a spin-orbit coupling. Using the central force not only saves labor but also allows us to consider the total spin s of the system and the angular momentum l as good quantum numbers; thus it is possible to solve, for each value of l , the system of equations obtained for each value of s . The phases and the cross sections are deduced according to the classical method of partial waves.

At low energy, the results are rather insensitive to the shape of the well, as we have seen from the Blatt and Jackson formula.

The potential shape used in this work is Gaussian,

$$V_0 f(\mu, r) = V_0 e^{-\mu r^2},$$

this form being the one which allows us to perform most of the algebra. The value of μ ($\mu = 0.2669 \cdot 10^{26} \text{ cm}^{-2}$) is that derived by Breit, Hoisington, and Share¹⁵ from analysis of low-energy proton-proton scattering, and has been used in previous four- and five-nucleon calculations (see Bransden review paper¹⁶). Assuming that the nuclear forces are charge-independent, this range can be used indifferently for p - p , n - n , or n - p interaction. The corresponding range $\rho_0 = 1/\sqrt{\mu} = 1.936 \cdot 10^{-13} \text{ cm}$ is larger than normal and in that respect can account, to a certain extent, for the effect of the neglected non-central forces.

The corresponding value of the depth V_0 (that is, $V_0 = -46.8 \text{ MeV}$) was interpolated from the results obtained by Burke¹⁷ for the determination of the well depth required to give the observed binding energy of the deuteron for a Gaussian well using $\mu = 0.2$ (0.1) 0.6.

2.- Trial Functions and the Variational Principle

With the interaction $V(r_{ij})$ defined previously, and T being the appropriate kinetic energy operator, the Hamiltonian will be

$$H = T + \sum_{\text{all pairs}} V(r_{ij}).$$

The wave function ψ to choose for the different nuclei in their ground states (D , T , He^3 , He^4) should be the exact solution of the Schrödinger equation,

$$(H - E) \psi = 0,$$

E being the corresponding binding energy.

As is well known, it is not possible, using Gaussian potential, to solve these equations and express the eigenfunctions in an analytical form. To allow for an analytical evaluation of most of the integrals, a trial function is chosen for the space part.

As the total wave function must be totally antisymmetric, and as the product of the spin and isotopic spin parts can be antisymmetrized for any number of nucleons up to four, it is possible to take a space part completely symmetric with respect to permutation of the nucleons. Among this class of function, the Gaussian form has been chosen.

$$\text{Deuteron:} \quad \phi = (1/N_0) [\exp(-\alpha r^2) + c \exp(-\beta r^2)] ;$$

$$T, He^3, He^4: \quad \phi = 1/N \exp [- (\lambda/2) \sum (ij)^2]$$

where N is the corresponding normalizing factor.

Writing $\psi = \phi \sigma$, and with λ being any of the parameters $\alpha, \beta, c, \lambda$, we have

$$E(\lambda) = \frac{\int \psi^* H \psi d\tau}{\int \psi^* \psi d\tau},$$

the integral sign involving the appropriate sums over the spin variables.

Then, according to the variational method, the parameters of the trial functions given above are determined so that

$$\delta E(\lambda) = \sum_i \frac{\partial E}{\partial \lambda_i} \delta \lambda_i = 0,$$

whatever the $\delta \lambda_i$ may be. This gives a system of simultaneous equations and therefore the values of λ_i .

The corresponding mean value E_{\min} so obtained is an upper limit for the binding energy E and verifies the equation

$$\int \psi^* (H - E_{\min}) \psi d\tau = 0.$$

This integral equation satisfied by the nuclear wave function is used later on to simplify the equations of the scattering problem.

The Gaussian form is

$$\phi = 1/N \exp \left[- (\lambda/2) \sum_{i < j} (ij)^2 \right],$$

where (ij) is any two-by-two combination of the $(1, 2, \dots, A)$ nucleons. Using the elementary relation of the moment of inertia,

$$\sum_i m_i M A_i^2 = \left(\sum_i m_i \right) M G^2 + \sum_i m_i G A_i^2,$$

G being the center of gravity, we get

$$\sum_{i < j} (ij)^2 = \sum_{p=1}^{A-1} \frac{A(A-p)}{A-p+1} R_p^2,$$

with

$$\vec{R}_p = \vec{r}_p - \frac{\vec{r}_{p+1} + \vec{r}_{p+2} \dots + \vec{r}_A}{A-p}.$$

The normalizing factor is easily deduced:

$$N^2 = \prod_{p=1}^{A-1} \left(\frac{\pi(A-p+1)}{\lambda A(A-p)} \right)^{3/2}$$

where \prod means the product of all terms obtained by using successively $p = 1, 2, \dots, A-1$.

The kinetic energy is given by

$$-\frac{\hbar^2}{M} \sum_{p=1}^{A-1} \frac{A-p+1}{2(A-p)} \nabla_{\vec{R}_p}^2$$

For each \vec{R}_p we get the contribution $\frac{\hbar^2}{M} \frac{3}{4} \lambda A$, and as we have $(A-1)$ different vectors \vec{R}_p , we get

$$\langle \phi | K.E. | \phi \rangle = \frac{\hbar^2}{M} \frac{3}{4} \lambda A(A-1).$$

The nuclear potential shape being $V(r) = V_0 e^{-\mu(rf)^2}$, we get

$$\langle \phi | V | \phi \rangle = \frac{A(A-1)}{2} (m+w) V_0 \left(\frac{A\lambda}{A\lambda+2\mu} \right)^{3/2}$$

The Coulomb potential gives

$$\langle \phi | V^c | \phi \rangle = \frac{Z(z-1)}{2} \frac{2e^2}{\sqrt{\pi}} \left(\frac{A\lambda}{2} \right)^{1/2}$$

And finally the binding energy is

$$BE(A, Z) = \frac{3}{4} \frac{\hbar^2}{M} \lambda A(A-1) + \frac{A(A-1)}{2} (m+w) V_0 \left(\frac{A\lambda}{A\lambda+2\mu} \right)^{3/2} + \frac{Z(z-1)}{2} \frac{2e^2}{\sqrt{\pi}} \left(\frac{A\lambda}{2} \right)^{1/2}$$

By making $A = 2, 3, 4$ one can get all the formulae needed for deuterons, tritons, He^3 , and He^4 .

Table I

Summary of Chapter II. Parameters used in the trial wave functions and corresponding calculated and experimental binding energies.

Nucleus	λ	E_{min} (MeV)	E_{exp} (MeV)
d	$\alpha = 0.0299 \times 10^{26} \text{ cm}^{-2}$ $\beta = 0.186 \times 10^{26} \text{ cm}^{-2}$ $c = 2.73$	- 2.133	- 2.226
t	0.15715	- 6.744	- 8.3
He^3	0.15400	- 5.975	- 7.55
He^4	0.15780	- 27.315	- 28.2

The potential range $\rho_0 = \frac{1}{\sqrt{\mu}} = 1.936 \times 10^{-13} \text{ cm}$ (from $\mu = 0.2669 \times 10^{26} \text{ c.m}^{-2}$) and depth $V_0 = -46.8 \text{ MeV}$ chosen can account for the binding energies of all the light nuclei we intend to deal with in our scattering problems. This is very important when dealing with coupled equations of a complete (elastic and nonelastic) system which has to be described with consistent parameters.

The values of the physical constants ($b, e, \text{etc.}$) used in the calculation are those given by DuMond and Cohen.¹⁸

III. Total Wave Function and Coupled Equations

A resonating-group wave function of correct symmetry may be written as

$$\begin{aligned}
\psi_s (A+1, A+2; 1, 2, \dots, A) &= \\
&= (1 - P_{A+1,1} - P_{A+1,3} - \dots) (1 - P_{A+2,2} - P_{A+2,4} - \dots) \\
\phi(A+1, A+2) \phi(1, 2, \dots, A) \sigma_s (A+1, A+2; 1, 2, \dots, A) F_s (A+1, A+2; \dots, A) \\
&+ [(1 - P_{A+1,1} - P_{A+1,3} - \dots) \phi(A+2, 1, 2, 3, \dots, A) \\
&\quad \sigma_s (A+1; A+2, 1, 2, 3, \dots, A) G_s (A+1; A+2, 1, 2, \dots, A)] \\
&+ [(1 - P_{A+2,2} - P_{A+2,4} - \dots) \phi(A+1, 1, 2, 3, \dots, A) \\
&\quad \sigma_s (A+1, 1, 2, 3, \dots, A) H_s (A+2; A+1, 1, 2, \dots, A)] .
\end{aligned}$$

where P_{ij} are exchange operators of Heisenberg type; σ_s is the spin function corresponding to the total spin S of the system of $1+2$ nucleons. As is well known, even though all spin orientations are contained in the usual beam, we may take only one definite spin orientation m_s for the spin function $\chi_s^{m_s}$ because different values of m_s lead to incoherent contributions. In fact, we have taken $m_s = S$ and dropped the superscript; F, G, H , are the scattering functions (to be replaced by plane wave in Born approximation), which we are going to determine by the partial-wave method, as described in Mott and Massey.¹²

The general way of deriving the coupled equations through the variational principle is given in Wheeler's fundamental paper, and the application to the case of $A = 2$ is given in detail in Burke and Laskar.⁶

The variational method leads to an integration over internal variables, and the appropriate differential volume elements are:

$$d\tau_1 = d(A+1, A+2) dR_1 dR_2 \dots dR_{A-1} ,$$

$$d\tau_2 = d(R_{A+2})_0 dR_1 dR_2 \dots dR_{A-1} ,$$

$$d\tau_3 = d(R_{A+1})_0 dR_1 dR_2 \dots dR_{A-1} ,$$

where we define

$$\vec{R}_{A+2} = \vec{r}_{A+2} - \frac{\vec{r}_1 + \vec{r}_2 + \dots + \vec{r}_A}{A}$$

or $A+1$ or $A+1$

The basic intergroup separation variables are

$$\vec{v} = \frac{\vec{r}_{A+1} + \vec{r}_{A+2}}{2} - \frac{\vec{r}_1 + \vec{r}_2 + \dots + \vec{r}_A}{A} \quad \text{for AA, AB, AC;}$$

$$\vec{v}_{1,2} = \vec{r}_{A+1,2} - \frac{\vec{r}_{A+2,1} + \vec{r}_1 + \vec{r}_2 + \dots + \vec{r}_A}{A+1} \quad \text{for the other elements.}$$

The exchange operators P_{ij} replace this set of \vec{v} by a set of \vec{r}' , and special care must be given to AA, AB, AC terms because of the occurrence of two types of exchanges.

First type of exchange:

$$AA \vec{r}' = \frac{\vec{r}_1 + \vec{r}_{A+2}}{2} - \frac{\vec{r}_{A+1} + \vec{r}_2 + \vec{r}_3 + \dots + \vec{r}_A}{A},$$

$$AB \vec{r}' = \vec{r}_{A+1} - \frac{\vec{r}_{A+2} + \vec{r}_1 + \vec{r}_2 + \dots + \vec{r}_A}{A+1}$$

Second type of exchange:

$$\vec{r}'_1 = \frac{\vec{r}_1 + \vec{r}_2}{2} - \frac{\vec{r}_{A+1} + \vec{r}_{A+2} + \vec{r}_3 + \dots + \vec{r}_A}{A}$$

$$\vec{r}' = \vec{r}_1 - \frac{\vec{r}_{A+2} + \vec{r}_{A+1} + \vec{r}_2 + \dots + \vec{r}_A}{A+1}$$

As already mentioned, BC belongs to the type $N(A, Z)$, and on that basis we have a single type of exchange:

$$\vec{r}' = \vec{r}_1 - \frac{\vec{r}_{A+1} + \vec{r}_2 + \dots + \vec{r}_A}{A} .$$

Consider now all the $\frac{(A+1)(A+2)}{2}$ interactions ($n-p$). They fall into different classes which can be listed and indicated as follows (where appearance of the same symbol indicates that the expressions are the same; the dagger is the classical adjoint symbol):

Type	AA		AB		BC
	First type of exchange	Second type of exchange	First type of exchange	Second type of exchange	
$(A-1, A)$	ν	ν	ν	ν	ν
$(1, i)$	x	x	ν	x	x
$(A+1, i)$	x^\dagger	ν	0	∇	x^\dagger
$(A+2, i)$	∇	∇	∇	∇	...
$(1, A+1)$	0	∇	0	0	0
$(1, A+2)$	\square^\dagger	∇	∇	0	...
$(A+1, A+2)$	\square	x	\square	\square	...
$(1, j)$...	ϕ			
$(2, j)$...	ϕ			
$(A+1, j)$...	ϕ^\dagger			
$(A+2, j)$...	ϕ^\dagger			

The BC term is dealt with in detail in UCRL 9674. In this table $i = 2, 3 \dots A$ except in $(AA|II)$ and BC where $i = 2$ only;

$$j = 3, \dots A.$$

Within a given column (AA, first type of exchange, for instance), all kernels corresponding to the same symbol are the same; for instance the $\frac{(A-1)(A-2)}{2}$ kernels interactions of the type (A-1, A) (in which neither neutron nor proton is A+1, A+2, or 1), are all the same.

Within a given column, (AA, first type of exchange for instance) the dagger signs correspond to the adjoint of the one without dagger; for instance

$$[AA | I | A+1, A+2] = [AA | I | 1, A+2]^\dagger .$$

The notation $[AA | I | np]$ speaks for itself: it means the kernel corresponding to the interaction np , in AA, first type of exchange.

The correspondence between kernels shown above is self-evident as soon as the interaction (np) is expressed in terms of the variables $\nu, r', R_2, \dots, R_{A-1}$, and allows for tremendous simplification in the formulation.

The following notations will be used:

$$\mathcal{E} = E_{\min}(D) + E_{\min}(A, Z) + E_d = E_{\min}(A+1, Z) + E_p = E_{\min}(A+1, Z+1) + E_n,$$

$$k^2 = \frac{2\mu_{d, n, \text{ or } p}}{\hbar^2} E_{d, n, \text{ or } p} ,$$

where $E_{d, n, \text{ or } p}$ is the kinetic energy of the corresponding particle in the center-of-mass frame, and

$$\frac{1}{\mu_d} = \frac{1}{M(D)} + \frac{1}{M(A, Z)} = \frac{A+2}{2AM} ,$$

$$\frac{1}{\mu_{n \text{ or } p}} = \frac{1}{M} + \frac{1}{(A+1)M} = \frac{A+2}{(A+1)M} ,$$

So that $\mathcal{E} = \mathcal{E}(k)$.

Also, \mathcal{N} is the kernel arising from the product of the initial-state wave function on the one hand and the final-state wave function after exchange on the other hand.

For each value of the total spin S of $(A + 2)$ nucleons we get a system of the type:

$$\begin{pmatrix} AA & AB & AC \\ BA & BB & BC \\ CA & CB & CC \end{pmatrix} \begin{pmatrix} F \\ G \\ H \end{pmatrix} = 0.$$

Some relations between the spin-dependent coefficients can easily be obtained by using the multiplication table given in the definition of the potential. For instance, we have, before any direct term,

$$\omega w + \mu m + \beta b + tb,$$

and before the corresponding kernel,

$$\mu w + \omega m + tb + \beta b.$$

Also

$$((AA | \text{I} | A+2, 2)) = (\omega' w + \mu' m + \beta' b + t' b) [AA | \text{I} | A+2, 2]$$

$$((AA | \text{II} | A+1, 1)) = (\mu' w + \omega' m + t' b + \beta' b) [AA | \text{II} | A+1, 1]$$

These spin-dependent coefficients are analyzed in a more detailed manner in UCRL 9674. The equation for the scattering of $D - He^4 \equiv (56) (1234)$ exists only for total spin $S = 1$ and is given as an exemple:

$$\begin{aligned}
\frac{3\beta^2}{8M} \left\{ \frac{d^2}{dr^2} - \frac{l(l+1)}{r^2} + k^2 \right\} f_l(r) &= \{2V_c^{62} + (8w - 2m + 4b - 4b)V^{15}\} f_l(r) \\
- \int_0^\infty \{2(T - \varepsilon \eta + (1|62)_c + (1|51)_c + (1|16 + 1|56)) \\
+ 6(w + m) ((1|12 + 1|52) + (1|34)) + (2w - 8m + 4b - 4b) (1|15) \\
+ (6w - 4m + 2b - 6b) (1|26)\} f_l(r') dr' \\
+ \int_0^\infty \{T - \varepsilon \eta + 2(\text{II}|62)_c + 2(\text{II}|12) + (\text{II}|34) \\
+ (4w - 6m + 6b - 2b) (\text{II}|15) \\
+ (4w + 4m - 2b - 2b) (\text{II}|13 + \text{II}|53)\} f_l(r') dr' .
\end{aligned}$$

IV. Solutions of the Equations and Calculation of Cross Sections

When we are left with the variables \vec{r} and \vec{r}' (after integrating over the other variables) the integration over the angular variables is carried out as usual.

$$F(\vec{r}) = \sum_l \frac{1}{r} f_l(r) P_l(\cos \theta) ,$$

$$K(\vec{r}, \vec{r}') = \sum_l \frac{2l+1}{4\pi r r'} K_l(r, r') P_l(\mu) .$$

and consequently $K(r, r') = 2\pi r r' \int_{-1}^{+1} K(\vec{r}, \vec{r}') P_l(\mu) d\mu$, where $K(\vec{r}, \vec{r}')$ is any of the kernels and F any scattering function, θ is the angle of scattering in the center-of-mass frame, and $\mu = \frac{(\vec{r}, \vec{r}')}{r r'}$.

The systems then obtained for each value of S are easily deduced from the previous one with $f_l(r)$ instead of $F(\vec{r})$, and $K_l(r, r')$ instead of $K(\vec{r}, \vec{r}')$, and are, of course, valid for the corresponding l value only. They are of the form

$$\left[\frac{d^2}{dr^2} - \frac{l(l+1)}{r^2} + k_\alpha^2 \right] f_l^\alpha(r) = U^{\alpha\alpha}(r) f_l^\alpha(r) + \int_0^\infty K_l^{\alpha 1}(r, r') f_l^1(r') dr' \quad (\text{IV, 1})$$

$$+ \int_0^\infty K_l^{\alpha 2}(r, r') f_l^2(r') dr' + \int_0^\infty K_l^{\alpha 3}(r, r') f_l^3(r') dr',$$

where $\alpha = 1, 2, 3$ is the channel index.

Using finite-difference approximations, Eqs. (IV. 1) are represented as a set of linear simultaneous equations, the unknown being the values of $f_l^\alpha(r)$ over the range of r required.⁴ For the three-channel case, for instance, it is necessary to find three independent solutions such that

$$f_l^{\alpha j}(r) = \frac{1}{\sqrt{v_\alpha}} [A_l^{\alpha j} F(r) + B_l^{\alpha j} G(r)]$$

for $\alpha = 1, 2, 3$ (three channels),

$j = 1, 2, 3$ (three independent solutions),

where $F_l^\alpha(r)$, $G_l^\alpha(r)$ are the regular and irregular wave function²⁰ for the corresponding channel α .

Then the reactance matrix is

$$R = \beta \mathbf{1}^{-1},$$

and the scattering matrix is

$$S = \frac{1 + iR}{1 - iR}.$$

The scattering amplitude $f_{\alpha' \alpha}^s(\theta)$ corresponding to the total spin S can be written

$$f_{\alpha' \alpha}^s(\theta) = -\frac{1}{2ik_\alpha} \sum_l (2l+1) P_l(\cos \theta) [\delta_{\alpha' \alpha} - S_{\alpha' \alpha}^l],$$

and the corresponding differential cross section is

$$\sigma_{\alpha' \alpha}^s(\theta) = |f_{\alpha' \alpha}^s(\theta)|^2.$$

Then the differential cross section is the appropriate weighted sum

$$\sigma_{\alpha' \alpha}(\theta) = \frac{1}{(2I_1 + 1)(2I_2 + 1)} \sum_s (2s + 1) \sigma_{\alpha' \alpha}^s(\theta),$$

where I_1 and I_2 are the spin of the colliding particles and s the spin of the whole system, $(2I_1 + 1)(2I_2 + 1)$ being the total number of spin states $(2s + 1)$ the number of states with spin s .^{13a}

VI. Conclusions

To appreciate the true value of Wheeler's method, it is useful to quote Blatt and Weisskopf.²¹

It is useful to divide the target nuclei into three categories

- A - Light nuclei $1 \leq A \leq 25$
- B - Intermediate nuclei $25 \leq A \leq 80$
- C - Heavy nuclei $80 \leq A \leq 240$

The light nuclei (group A) must be treated individually. It is almost impossible to apply any general rules describing nuclear reactions in that group. The assumptions made in the preceding chapter about the interior of the nucleus are not applicable to group A, since there are too few nucleons in these nuclei for a well-defined interior region. All nucleons are at the "surface" of the nucleus.

Two cases that are beyond the scope of this paper have also been treated, namely the elastic scattering of six nucleons ($t - t$ reactions) by Bransden and Hamilton,²² and of eight nucleons ($\alpha - \alpha$ reactions) by Butcher and McNamen²³ and Schmid and Wildermuth.²⁴

In each case, numerical results have been obtained and compared with experimental data;²⁵ the relative merits of different types of forces have been investigated and conclusions have been drawn.

The main point of this conclusion is that the resonating-group structure¹ can well explain all the experimental results obtained on the few-nucleon scattering experiments. As pointed out by Bransden,¹⁶ it is a means of correlating data with just a few parameters, namely the range and depth of the potential and the exchange type of force. Although in particular cases one type of force can fit better than another one, it is remarkable that the Serber type fits all cases reasonably well.

The central two-body potential with central forces can be criticized, but the inclusion of a noncentral force and particularly of a tensor force makes the problem enormously complicated.

Also the Gaussian shape adopted for the nuclear wave function can be criticized as being too rapidly cut off, but it is possible to apply the same general method to any other type of wave function, and particularly the Irving type,²⁶ to build up general formulae for kernels and direct terms in terms of the numbers of nucleons A involved in the target nucleus.

Finally, it is also suggested that the work be extended to cases $A > 4$ by using wave functions of the appropriate symmetry, and to the cases $(A' Z')(A, Z)$ by using the general form of the wave function, both for the incident and the target nuclei, to include, for instance $t - t$ and $\alpha - \alpha$ reactions.

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